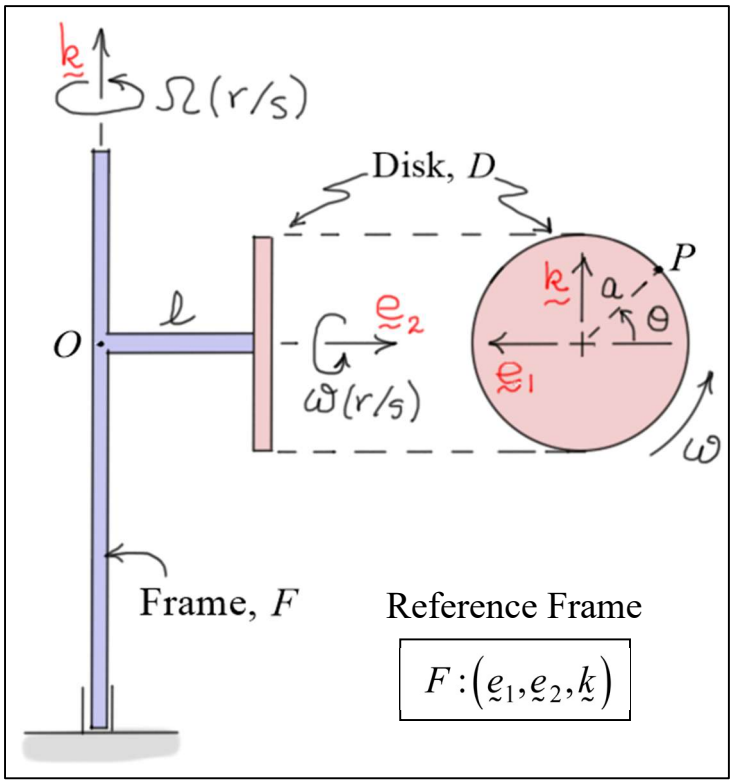**Intermediate Dynamics**
**Example System I**