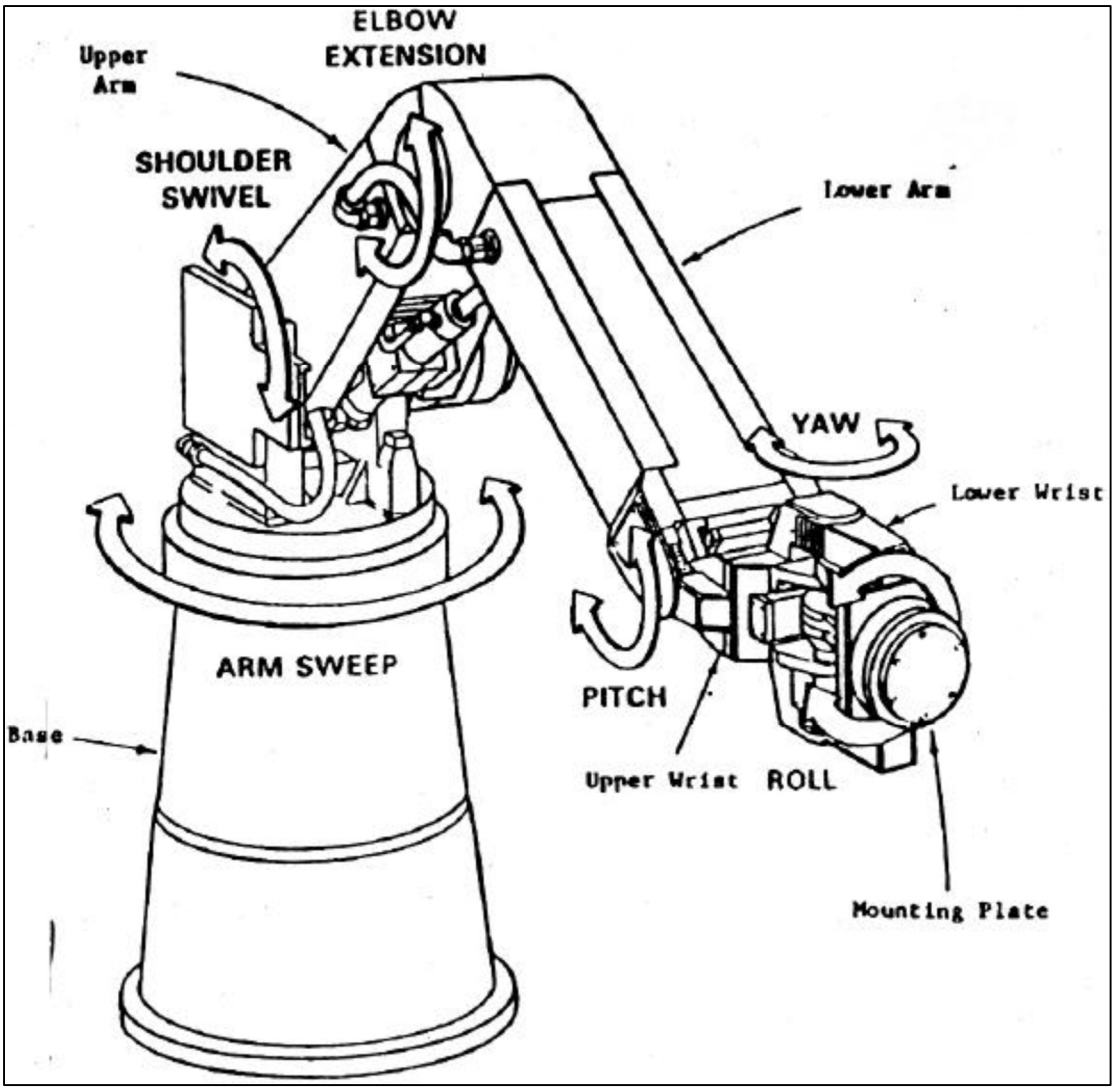Intermediate Dynamics
Mechanical Configuration of T3 Robot