

# Elementary Engineering Mathematics

## The Derivative of a Function as a Function

Previously, we learned about the meaning of the derivative of a function  $f(x)$  at some arbitrary point  $x_0$ . The derivative  $f'(x_0)$  is simply the slope of the tangent line at  $x_0$ . We now consider the function  $f'(x)$  or  $\frac{df}{dx}(x)$  which consists of the derivatives of  $f(x)$  at all points within the range of  $x$ . The following table gives the derivatives of some common functions used in engineering.

Name	Function, $f(x)$	Derivative, $f'(x) = \frac{df}{dx}(x)$
Constant	$a$	0
Polynomial terms	$ax^n$	$nax^{n-1}$
Exponential	$e^{ax}$	$ae^{ax}$
Sine	$\sin(ax)$	$a \cos(ax)$
Cosine	$\cos(ax)$	$-a \sin(ax)$

To evaluate the derivative at some point  $x_0$ , we can simply evaluate the derivative function  $f'(x)$  at  $x_0$ .

These results can be extended to combinations of functions by using the following *rules* for differentiation.

Diagonal	Name	Formula
1	Summation rule	$\frac{d}{dx}(f(x) + g(x)) = f'(x) + g'(x)$
2	Multiplication by a constant, $a$	$\frac{d}{dx}(af(x)) = a f'(x)$
3	Product rule	$\frac{d}{dx}(f(x)g(x)) = f'(x)g(x) + f(x)g'(x)$
4	Chain rule	$\frac{d}{dx}(f(y(x))) = \frac{df}{dy} \frac{dy}{dx} = \frac{df}{dy} y'(x)$

### Example 1:

Given: The path of a golf ball as a function of horizontal position

$$y = f(x) = 73.54 \left( \frac{x}{61.71} \right) - 16.1 \left( \frac{x}{61.71} \right)^2 = 1.1917 x - (4.2278 \times 10^{-3}) x^2 \quad (1)$$

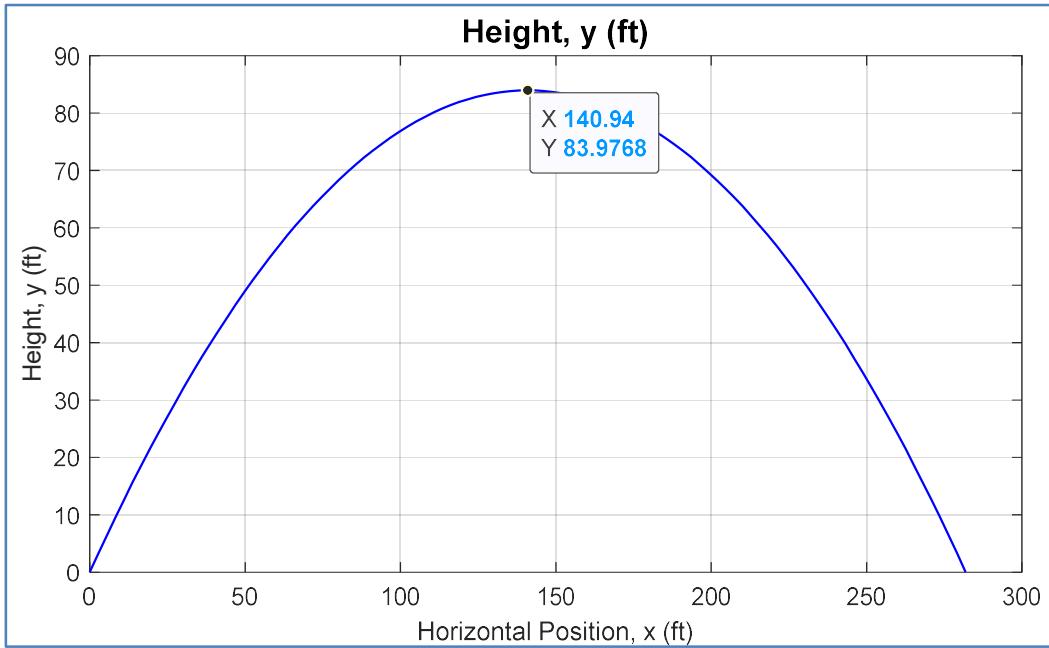


Figure 1. Height of Golf Ball as a Function of Distance,  $x$

Recall that the **velocity** of the ball is in the direction of the tangent line.

Find: (a) The **derivative function**  $f'(x)$ , (b) the derivative at  $x = x_0 = 50$  (ft) and  $x = x_0 = 200$  (ft), (c) the maximum height of the ball, (d) a plot of function  $f'(x)$ , and (e) the second derivative function  $f''(x) = df'/dx$ .

Solution:

(a) Using rule 1 above, we can find the derivative function  $f'(x)$ .

$$\begin{aligned} f'(x) &= \frac{d}{dx} \left( 1.1917 x - (4.2278 \times 10^{-3}) x^2 \right) = \frac{d}{dx} (1.1917 x) - \frac{d}{dx} ((4.2278 \times 10^{-3}) x^2) \\ &= 1.1917 \frac{d}{dx} (x) - (4.2278 \times 10^{-3}) \frac{d}{dx} (x^2) \\ &= (1.1917 \times 1) - (4.2278 \times 10^{-3}) (2x) \end{aligned}$$

or

$$f'(x) = 1.1917 - (8.4556 \times 10^{-3}) x \quad (2)$$

(b) We can use the derivative function in Eq. (2) to find the derivative of the quadratic function at any point in the domain of  $x$ .

$$\text{At } x = x_0 = 50 \text{ (ft)}: \boxed{f'(x)|_{x=50} = 1.1917 - (8.4556 \times 10^{-3})(50) \approx 0.76892 \approx 0.769}$$

$$\text{At } x = x_0 = 200 \text{ (ft)}: \boxed{f'(x)|_{x=200} = 1.1917 - (8.4556 \times 10^{-3})(200) \approx -0.49942 \approx -0.499}$$

(c) The maximum height of the ball occurs where the slope of the tangent line is zero.

$$f'(\hat{x}) = 0 = 1.1917 - (8.4556 \times 10^{-3})\hat{x} \Rightarrow \boxed{\hat{x} = 1.1917 / 8.4556 \times 10^{-3} = 140.94 \text{ (ft)}}$$

$$y_{\max} = f(\hat{x}) = 1.1917 \hat{x} - (4.2278 \times 10^{-3})\hat{x}^2 \Rightarrow \boxed{y_{\max} = 83.977 \approx 84 \text{ (ft)}}$$

(d) The plot of  $f'(x)$  indicates that the slope of  $f(x)$  is positive over the first half of the range of  $x$ , negative over the second half, and zero at the maximum height of the ball. This confirms the fact that the function reached a **maximum** at this point, and **not a minimum**. When  $f'(x)$  is positive,  $f(x)$  is increasing, and when  $f'(x)$  is negative,  $f(x)$  is decreasing.

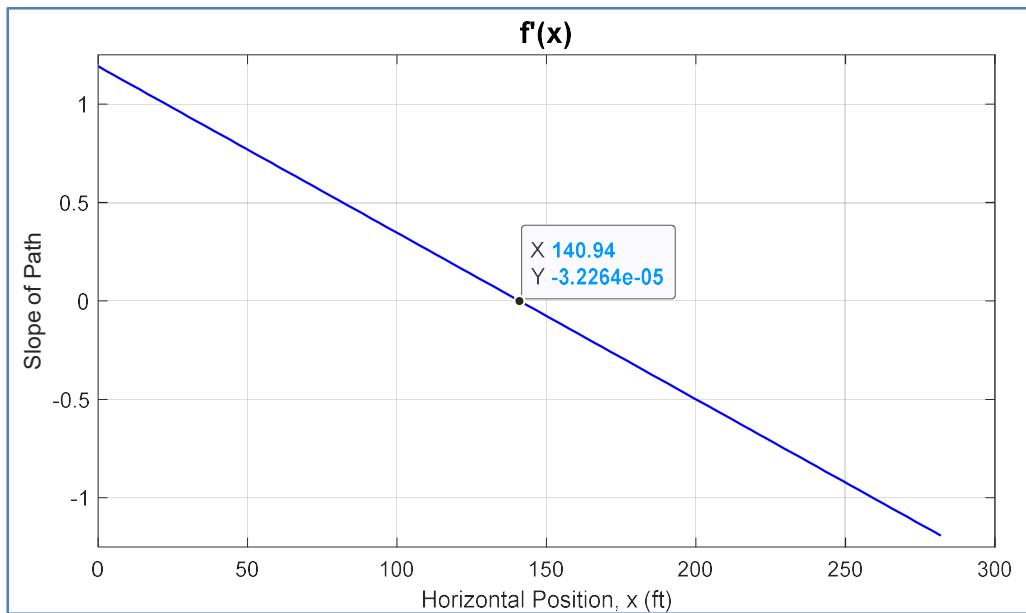


Figure 2. Slope of the Path of the Golf Ball as a Function of  $x$

(e) Using rule 1, 
$$\boxed{f''(x) = \frac{d}{dx} [1.1917 - (8.4556 \times 10^{-3})x] = -8.4556 \times 10^{-3} < 0}$$
. This again

confirms that the function is maximum at this point. If  $f''(\hat{x}) < 0$ , the function is at a **local maximum**, and if  $f''(\hat{x}) > 0$ , the function is at a **local minimum**.

### Example 2:

Given: The height of a golf ball as a function of time

$$y = f(t) = 73.54t - 16.1t^2$$

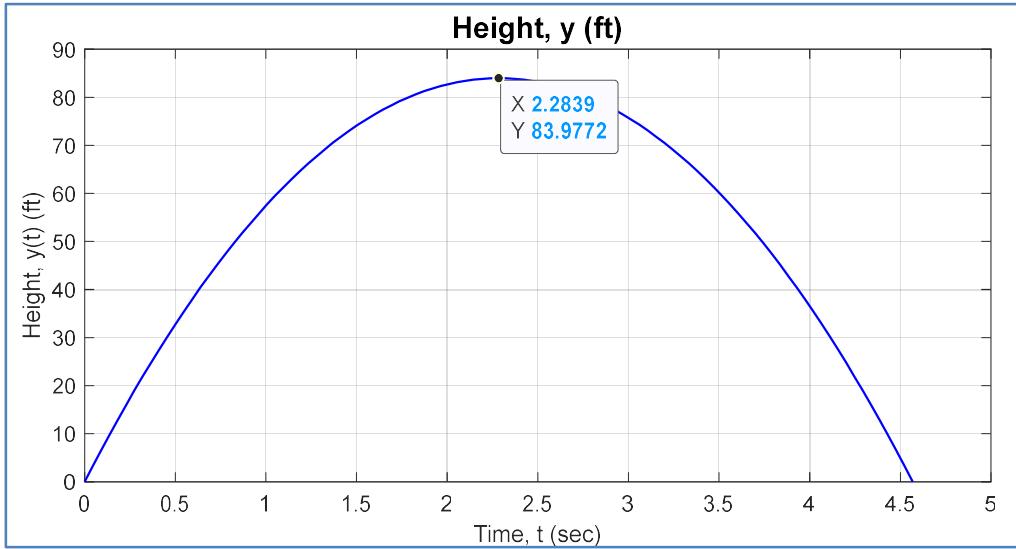


Figure 3. Height of the Ball as a Function of Time

Find: (a) the derivative function  $f'(t)$ , (b) the slope of  $f(t)$  at  $t = 0.5$  (sec), and (c) the time  $\hat{t}$  when the ball reaches maximum height.

Solution:

(a) We can again use rule 1 to find  $f'(t)$ .

$$\frac{dy}{dt} = f'(t) = (73.54 \times 1) - 16.1(2t) = 73.54 - 32.2t$$

(b) When  $t = 0.5$  (sec),  $\left. \frac{dy}{dt} \right|_{t=0.5} = f'(t) \Big|_{t=0.5} = 73.54 - (32.2 \times 0.5) \approx 57.44$  (ft/sec). This is the

velocity of the ball in the  $Y$ -direction at this instant.

(c) To find time  $\hat{t}$ , we set  $f'(\hat{t}) = 0$ , and solve

$$f'(\hat{t}) = 0 = 73.54 - 32.2\hat{t} \Rightarrow \hat{t} = 73.54/32.2 \approx 2.2839 \approx 2.28 \text{ (sec)}$$

### Example 3:

Given: The horizontal position and height of a golf ball are functions of time

$$\boxed{x(t) = 61.71t} \quad \boxed{y(t) = 73.54t - 16.1t^2} \quad (3)$$

Find: The velocity vector of the ball when  $x = x_0 = 50$  (ft).

Solution:

The components of the velocity of the ball in the  $X$  and  $Y$  directions are given by the derivatives of Eqs. (3) with respect to time. We must first find the time  $\hat{t}$  required to get to  $x = x_0 = 50$  (ft).

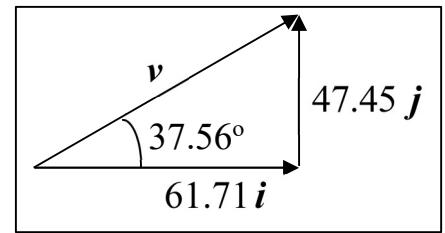
$$x(\hat{t}) = 50 = 61.71\hat{t} \Rightarrow \hat{t} = 50 / 61.71 \approx 0.81024 \text{ (sec)}$$

$$\boxed{v_x(t) = \frac{dx}{dt} = \dot{x}(t) = 61.71 \times (1) \approx 61.71 \text{ (ft/sec)}} \quad (\text{same at all } t)$$

$$\boxed{v_y(t) = \frac{dy}{dt} = \dot{y}(t) = 73.54 - 32.2t}$$

$$\Rightarrow \boxed{v_y(\hat{t}) = 73.54 - (32.2 \times 0.81024) \approx 47.45 \text{ (ft/sec)}}$$

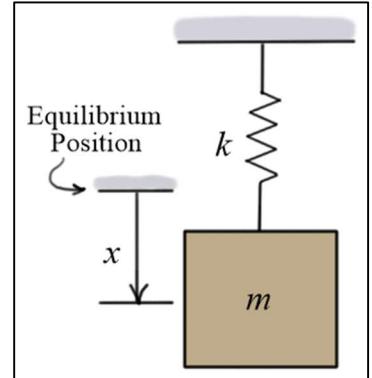
So, at  $x = x_0 = 50$  (ft), we have  $\boxed{\underline{v} = 61.71 \underline{i} + 47.45 \underline{j} \text{ (ft/sec)}}$



### Example 4: Undamped, free vibration

Given: In response to the initial position  $x_0$  and initial velocity  $v_0$ , the undamped spring-mass-damper system has displacement function

$$\boxed{x(t) = \frac{v_0}{\omega} \sin(\omega t) + x_0 \cos(\omega t)} \quad \boxed{\omega = \sqrt{\frac{k}{m}}}$$



Find: (a) the velocity function  $v(t) = \dot{x}(t)$ , (b) the acceleration function  $a(t) = \ddot{x}(t)$ , (c)  $x(0)$ ,  $v(0)$ , and  $a(0)$ , the position, velocity and acceleration of the mass at  $t = 0$ , and (d) the times when  $x(t)$  has a maximum or minimum if  $v_0 = 0$ , and verify which are maxima and which are minima.

### Solution:

(a) Using rules 1 and 2:

$$\begin{aligned}
 v(t) &= \dot{x}(t) = \frac{d}{dt} \left[ \frac{v_0}{\omega} \sin(\omega t) + x_0 \cos(\omega t) \right] = \frac{d}{dt} \left[ \frac{v_0}{\omega} \sin(\omega t) \right] + \frac{d}{dt} \left[ x_0 \cos(\omega t) \right] \\
 &= \frac{v_0}{\omega} \cancel{\cos(\omega t)} - x_0 \omega \sin(\omega t) \\
 \boxed{v(t) = v_0 \cos(\omega t) - x_0 \omega \sin(\omega t)}
 \end{aligned}$$

(b) Again, using rules 1 and 2:

$$\begin{aligned}
 a(t) &= \ddot{x}(t) = \dot{v}(t) = \frac{d}{dt} \left[ v_0 \cos(\omega t) - x_0 \omega \sin(\omega t) \right] \\
 &= \frac{d}{dt} \left[ v_0 \cos(\omega t) \right] - \frac{d}{dt} \left[ x_0 \omega \sin(\omega t) \right] \\
 \boxed{a(t) = -v_0 \omega \sin(\omega t) - x_0 \omega^2 \cos(\omega t)}
 \end{aligned}$$

(c)  $x(0) = \frac{v_0}{\omega} \sin(0) + x_0 \cos(0) = x_0$   $v(0) = v_0 \cos(0) - x_0 \omega \sin(0) = v_0$  (checks)

$$\boxed{a(0) = -v_0 \omega \sin(0) - x_0 \omega^2 \cos(0) = -x_0 \omega^2}$$

(d) If  $v_0 = 0$ , the velocity and acceleration of the mass are  $\boxed{v(t) = -x_0 \omega \sin(\omega t)}$  and

$\boxed{a(t) = -x_0 \omega^2 \cos(\omega t)}$ . The position has a maximum or minimum at times  $\hat{t}$  when the velocity  $v(\hat{t}) = 0$ . So, the position will be a maximum or minimum when  $\omega \hat{t} = n\pi$  or  $\boxed{\hat{t} = n\pi/\omega}$  ( $n = 0, 1, 2, \dots$ ). The results are summarized in the following table.

$n$	$v(\hat{t})$	$a(\hat{t})$	Type
$0, 2, 4, \dots$	zero	negative	maximum
$1, 3, 5, \dots$	zero	positive	minimum

The figure below shows the position, velocity, and acceleration functions for  $x_0 = 0.25$  (ft) and  $\omega = 2\pi/3$  (rad/s). When the velocity is zero, the displacement is either a maximum or minimum. It is a maximum when the acceleration is negative, and it is a minimum when the acceleration is positive (as indicated in the table above).

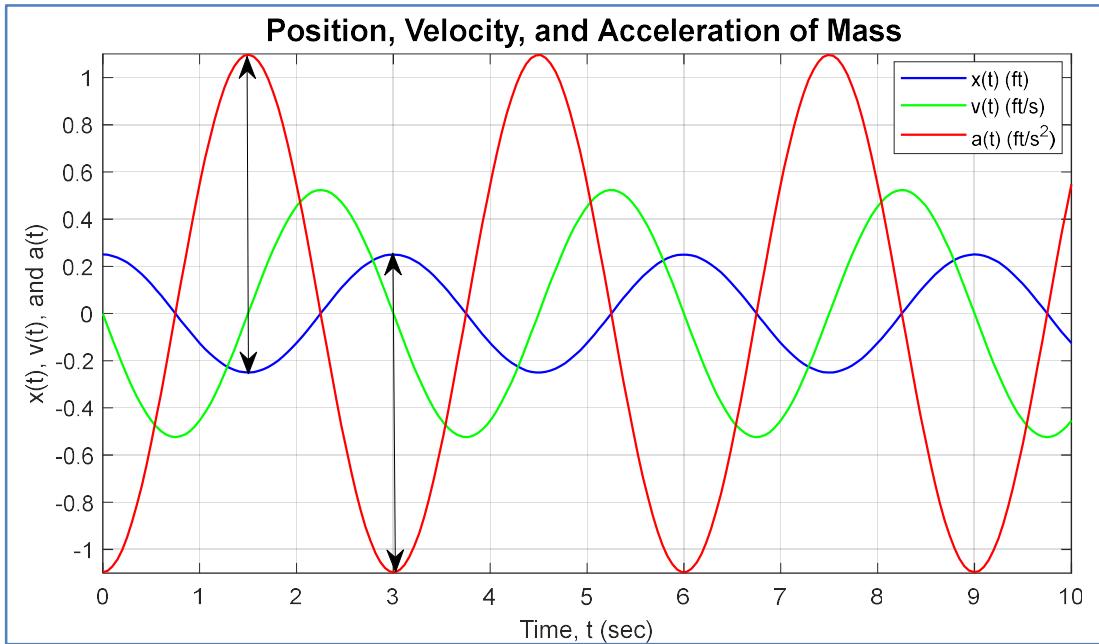
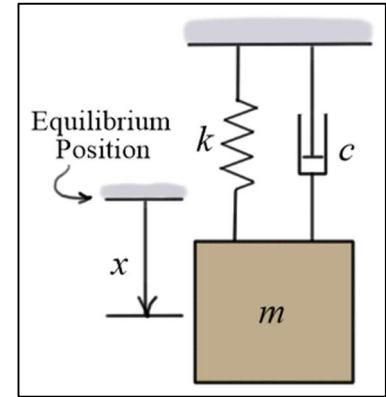


Figure 4. Position, Velocity, and Acceleration of Mass Due to Initial Displacement

Example 5: Over-damped, free vibration

Given: In response to the initial conditions  $x_0 = 0.25 (ft) and  $v_0 = 5$  (ft/s), the over-damped spring-mass-damper system has displacement$

$$x(t) = (0.5163)e^{-3.82t} - (0.2663)e^{-26.18t} \text{ (ft)}$$



Find: (a) the velocity function  $v(t) = \dot{x}(t)$ ; (b) the acceleration function  $a(t) = \ddot{v}(t) = \ddot{x}(t)$ ; (c)  $x(0)$ ,  $v(0)$ , and  $a(0)$ , the position, velocity and acceleration of the mass at  $t = 0$ ; and (d) find the time when the displacement is maximum.

Solution:

(a) Using rules 1 and 2, we find  $v(t)$

$$\begin{aligned} v(t) &= \dot{x}(t) = \frac{d}{dt} \left( (0.5163)e^{-3.82t} - (0.2663)e^{-26.18t} \right) \\ &= \frac{d}{dt} \left[ (0.5163)e^{-3.82t} \right] - \frac{d}{dt} \left[ (0.2663)e^{-26.18t} \right] \\ &= (0.5163)(-3.82)e^{-3.82t} - (0.2663)(-26.18)e^{-26.18t} \end{aligned}$$

$$v(t) = -1.9723e^{-3.82t} + 6.9717e^{-26.18t} \text{ (ft/s)}$$

(b) Using rules 1 and 2 again, we find  $a(t)$

$$\begin{aligned}
 a(t) &= \ddot{x}(t) = \dot{v}(t) = \frac{d}{dt} \left[ -1.9723e^{-3.82t} + 6.9717e^{-26.18t} \right] \\
 &= (-1.9723)(-3.82)e^{-3.82t} + (6.9717)(-26.18)e^{-26.18t} \\
 a(t) &= 7.5342e^{-3.82t} - 182.52e^{-26.18t} \text{ (ft/s}^2\text{)}
 \end{aligned}$$

$$(c) x(0) = ((0.5163)e^0 - (0.2663)e^0) = 0.5163 - 0.2663 = 0.25 \text{ (ft)} \text{ (checks)}$$

$$\begin{aligned}
 v(0) &= -1.9723e^0 + 6.9717e^0 = 6.9717 - 1.9723 = 4.9994 \approx 5 \text{ (ft/s)} \text{ (checks)} \\
 a(0) &= 7.5342e^0 - 182.52e^0 = 7.5342 - 182.52 \approx -175 \text{ (ft/s}^2\text{)}
 \end{aligned}$$

(d) To find the time when the displacement is maximum, we set  $dx(t)/dt = v(t) = 0$ .

$$\begin{aligned}
 v(t) &= -1.9723e^{-3.82t} + 6.9717e^{-26.18t} = 0 \Rightarrow 6.9717e^{-26.18t} = 1.9723e^{-3.82t} \\
 \Rightarrow \frac{6.9717}{1.9723} &= 3.5348 = \frac{e^{-3.82t}}{e^{-26.18t}} = e^{22.36t} \Rightarrow \ln(3.5348) = \ln(e^{22.36t}) = 22.36t
 \end{aligned}$$

$$t = \ln(3.5348)/22.36 = 0.0565 \text{ (sec)}$$

$$x(0.0565) = (0.5163)e^{-0.21583} - (0.2663)e^{-1.4792} = 0.355 \text{ (ft)}$$

$$a(0.0565) = 7.5342e^{-0.21583} - 182.52e^{-1.4792} = -35.5 \text{ (ft/s}^2\text{)} \text{ (indicates maximum)}$$

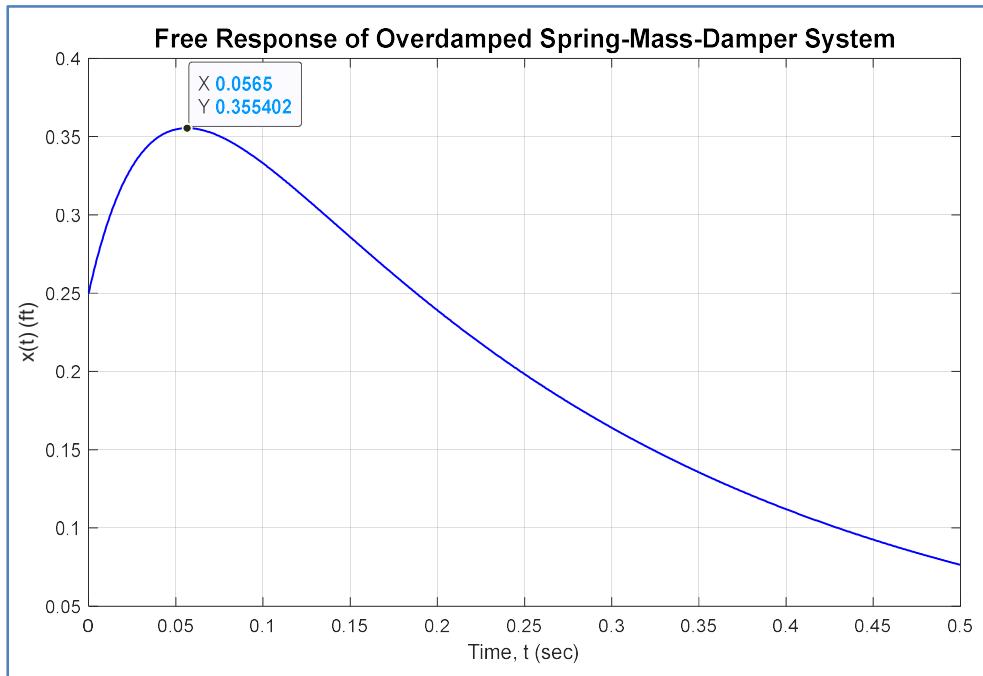


Figure 5. Response of Overdamped Spring-Mass-Damper System

### Example 6: Under-damped, free vibration

Given: In response to the initial conditions  $x_0 = 0.25$  (ft) and  $v_0 = 5$  (ft/s), the under-damped spring-mass-damper system has displacement

$$x(t) = e^{-5t} \left[ 0.7217 \sin(\sqrt{75} t) + 0.25 \cos(\sqrt{75} t) \right] \text{ (ft)}$$

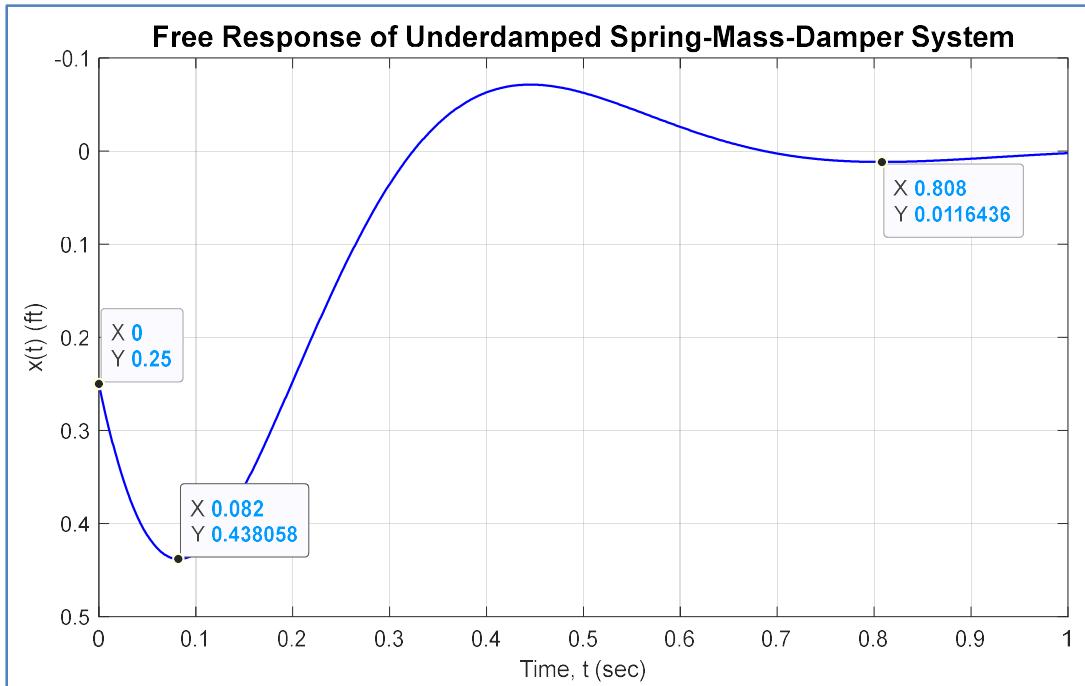
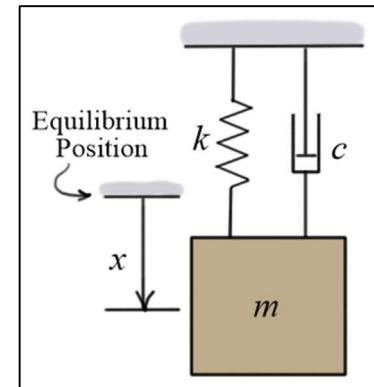


Figure 6. Response of Underdamped Spring-Mass-Damper System

Find: (a) the velocity function  $v(t) = \dot{x}(t)$ , (b) the acceleration function  $a(t) = \ddot{x}(t)$ , and (c)  $x(0)$ ,  $v(0)$ , and  $a(0)$ , the position, velocity and acceleration of the mass at  $t = 0$ .

Solution:

(a) Using rules 2, 3 and 4, we find the velocity function  $v(t)$

$$v(t) = \dot{x}(t)$$

$$\begin{aligned} &= \frac{d}{dt} \left( e^{-5t} \left[ 0.7217 \sin(\sqrt{75} t) + 0.25 \cos(\sqrt{75} t) \right] \right) \\ &= \frac{d}{dt} \left( e^{-5t} \right) \times \left[ 0.7217 \sin(\sqrt{75} t) + 0.25 \cos(\sqrt{75} t) \right] \\ &\quad + e^{-5t} \left( \frac{d}{dt} \left[ 0.7217 \sin(\sqrt{75} t) + 0.25 \cos(\sqrt{75} t) \right] \right) \\ &= \dots \end{aligned}$$

$$\begin{aligned}
&= -5e^{-5t} \left[ 0.7217 \sin(\sqrt{75}t) + 0.25 \cos(\sqrt{75}t) \right] \\
&\quad + e^{-5t} \left( (0.7217)\sqrt{75} \cos(\sqrt{75}t) - (0.25)\sqrt{75} \sin(\sqrt{75}t) \right) \\
&= e^{-5t} \left[ -((5 \times 0.7217) + (0.25 \times \sqrt{75})) \sin(\sqrt{75}t) \right] \\
&\quad + e^{-5t} \left[ ((0.7217\sqrt{75}) - (5 \times 0.25)) \cos(\sqrt{75}t) \right] \\
\Rightarrow & \boxed{v(t) = e^{-5t} \left[ -5.7736 \sin(\sqrt{75}t) + 5 \cos(\sqrt{75}t) \right] \text{ (ft/s)}}
\end{aligned}$$

(b) Using rules 2, 3 and 4, we find the acceleration function  $a(t)$

$$\begin{aligned}
a(t) &= \ddot{x}(t) = \dot{v}(t) \\
&= \frac{d}{dt} \left( e^{-5t} \left[ -5.7736 \sin(\sqrt{75}t) + 5 \cos(\sqrt{75}t) \right] \right) \\
&= \frac{d}{dt} \left( e^{-5t} \right) \times \left[ -5.7736 \sin(\sqrt{75}t) + 5 \cos(\sqrt{75}t) \right] \\
&\quad + e^{-5t} \left( \frac{d}{dt} \left[ -5.7736 \sin(\sqrt{75}t) + 5 \cos(\sqrt{75}t) \right] \right) \\
&= -5e^{-5t} \left[ -5.7736 \sin(\sqrt{75}t) + 5 \cos(\sqrt{75}t) \right] \\
&\quad + e^{-5t} \left( (-5.7736\sqrt{75}) \cos(\sqrt{75}t) - (5)\sqrt{75} \sin(\sqrt{75}t) \right) \\
&= e^{-5t} \left[ ((5 \times 5.7736) - (5\sqrt{75})) \sin(\sqrt{75}t) \right] \\
&\quad + e^{-5t} \left[ -((5.7736\sqrt{75}) + (5 \times 5)) \cos(\sqrt{75}t) \right] \\
\Rightarrow & \boxed{a(t) = -e^{-5t} \left[ 14.43 \sin(\sqrt{75}t) + 75 \cos(\sqrt{75}t) \right] \text{ (ft/s}^2\text{)}}
\end{aligned}$$

(c)  $x(0) = e^0 \left[ 0.7217 \sin(0) + 0.25 \cos(0) \right] = 0.25 \text{ (ft)} \quad \text{(checks)}$

$$\boxed{v(0) = e^0 \left[ -5.7736 \sin(0) + 5 \cos(0) \right] = 5 \text{ (ft/s)} \quad \text{(checks)}}$$

$$\boxed{a(0) = -e^0 \left[ 14.43 \sin(0) + 75 \cos(0) \right] = -75 \text{ (ft/s}^2\text{)}}$$

At time  $t = 0$ , the mass is **moving downward** at 5 (ft/s), but it is **slowing down** at a rate of 75 (ft/s<sup>2</sup>). According to Figure 6, the mass reaches a **zero downward velocity** at about  $t \approx 0.082$  (sec).