

Elementary Dynamics Example #38a: (Rigid Body Kinematics – Sliding Contact Acceleration)

Given: $v_A = 2 \text{ (ft/s)} = \text{constant}$, $\theta = 30 \text{ (deg)}$

Find: a) ω_{AB} , $\dot{\ell}$, b) α_{AB} , $\ddot{\ell}$

Solution #1: using the unit vectors ($\hat{i}, \hat{j}, \hat{k}$)

a) Using the velocity equation for sliding contacts, write

$$\mathbf{v}_C = \mathbf{v}_A + (\boldsymbol{\omega}_{AB} \times \mathbf{r}_{C/A}) + \mathbf{v}_{C_{\text{rel}}} \quad * \text{ (C is fixed, but moves on AB)}$$

Here,

$$\mathbf{v}_C = \mathbf{0} \quad \mathbf{v}_A = 2(-\cos(20)\hat{i} + \sin(20)\hat{j})$$

$$\boldsymbol{\omega}_{AB} \times \mathbf{r}_{C/A} = \omega_{AB} \hat{k} \times (4.5\hat{i} + 2.5\hat{j}) = \omega_{AB}(-2.5\hat{i} + 4.5\hat{j})$$

$$\mathbf{v}_{C_{\text{rel}}} = \dot{\ell} \mathbf{e}_1 = \dot{\ell}(4.5\hat{i} + 2.5\hat{j})/\ell = \dot{\ell}(4.5\hat{i} + 2.5\hat{j})/\sqrt{4.5^2 + 2.5^2} \quad (\text{velocity of C on AB})$$

Substituting into the velocity equation (*) gives the following scalar equations.

$$\begin{cases} 0 = -2\cos(20) - 2.5\omega_{AB} + \left(\frac{4.5}{\ell}\right)\dot{\ell} \\ 0 = 2\sin(20) + 4.5\omega_{AB} + \left(\frac{2.5}{\ell}\right)\dot{\ell} \end{cases} \dots \text{solving gives} \Rightarrow \begin{cases} \omega_{AB} \approx -0.293458 \approx -0.293 \text{ (r/s)} \\ \dot{\ell} \approx 1.31068 \approx 1.31 \text{ (ft/s)} \end{cases}$$

b) Using the acceleration equation for sliding contacts, write

$$\mathbf{a}_C = \mathbf{a}_A + (\boldsymbol{\alpha}_{AB} \times \mathbf{r}_{C/A}) - \omega_{AB}^2 \mathbf{r}_{C/A} + \mathbf{a}_{C_{\text{rel}}} + 2(\boldsymbol{\omega}_{AB} \times \mathbf{v}_{C_{\text{rel}}}) \quad ** \text{ (C is fixed, but moves on AB)}$$

Here,

$$\mathbf{a}_C = \mathbf{a}_A = \mathbf{0}$$

$$\boldsymbol{\alpha}_{AB} \times \mathbf{r}_{C/A} = \alpha_{AB} \hat{k} \times (4.5\hat{i} + 2.5\hat{j}) = \alpha_{AB}(-2.5\hat{i} + 4.5\hat{j}) \quad -\omega_{AB}^2 \mathbf{r}_{C/A} = -\omega_{AB}^2(4.5\hat{i} + 2.5\hat{j})$$

$$\mathbf{a}_{C_{\text{rel}}} = \ddot{\ell} \mathbf{e}_1 = \ddot{\ell}(4.5\hat{i} + 2.5\hat{j})/\ell = \ddot{\ell}(4.5\hat{i} + 2.5\hat{j})/\sqrt{4.5^2 + 2.5^2} \quad (\text{acceleration of C on AB})$$

$$2(\boldsymbol{\omega}_{AB} \times \mathbf{v}_{C_{\text{rel}}}) = 2\omega_{AB} \hat{k} \times \dot{\ell}(4.5\hat{i} + 2.5\hat{j})/\ell = \left(\frac{2\omega_{AB}\dot{\ell}}{\ell}\right)(-2.5\hat{i} + 4.5\hat{j})$$

Substituting into the acceleration equation (**) gives the following scalar equations.

$$\begin{cases} 0 = -2.5\alpha_{AB} - 4.5\omega_{AB}^2 + \left(\frac{4.5}{\ell}\right)\ddot{\ell} - \left(\frac{5\omega_{AB}\dot{\ell}}{\ell}\right) \\ 0 = 4.5\alpha_{AB} - 2.5\omega_{AB}^2 + \left(\frac{2.5}{\ell}\right)\ddot{\ell} + \left(\frac{9\omega_{AB}\dot{\ell}}{\ell}\right) \end{cases} \dots \text{solving gives} \Rightarrow \begin{cases} \alpha_{AB} \approx 0.149434 \approx 0.149 \text{ (r/s}^2\text{)} \\ \ddot{\ell} \approx 0.443318 \approx 0.443 \text{ (ft/s}^2\text{)} \end{cases}$$

Conclusions:

1. Bar AB is rotating clockwise ($\omega_{AB} < 0$), but slowing down ($\alpha_{AB} > 0$).
2. Point C is moving away from point A ($\dot{\ell} > 0$) at an increasing rate ($\ddot{\ell} > 0$).

